

# Earth rotation parameters from satellite techniques

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# Overview

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- Sub-daily Earth rotation:
  - GPS, GLONASS and SLR
  - Time-series (up to 1-hour resolution)
- Impact of gravity field variations on ERPs:
  - Estimation of low-degree gravity field coefficients together with ERPs
  - GNSS and SLR solutions

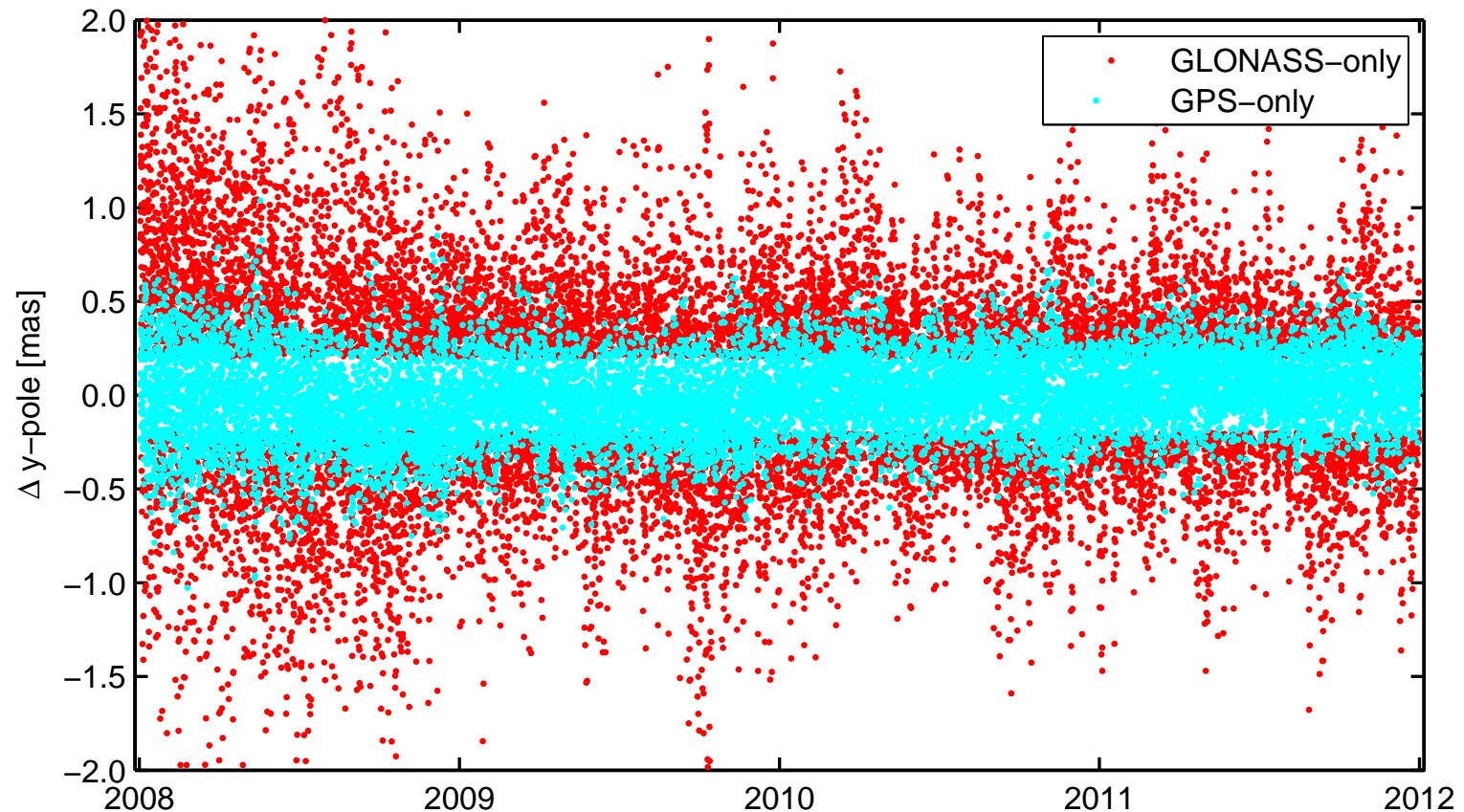
# Sub-daily ERPs

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## Comparison of different satellite systems:

- **GPS-only:**
  - 2008 – 2011
  - Daily solutions
  - 1.5 hour temporal resolution
- **GLONASS-only:**
  - Settings / network identical to GPS-only solution
- **LAGEOS-only:**
  - 2001 – 2011
  - Weekly solutions
  - Testing different temporal resolutions (1 h, 2 h, 3 h)

# Sub-daily ERPs: Time series PM

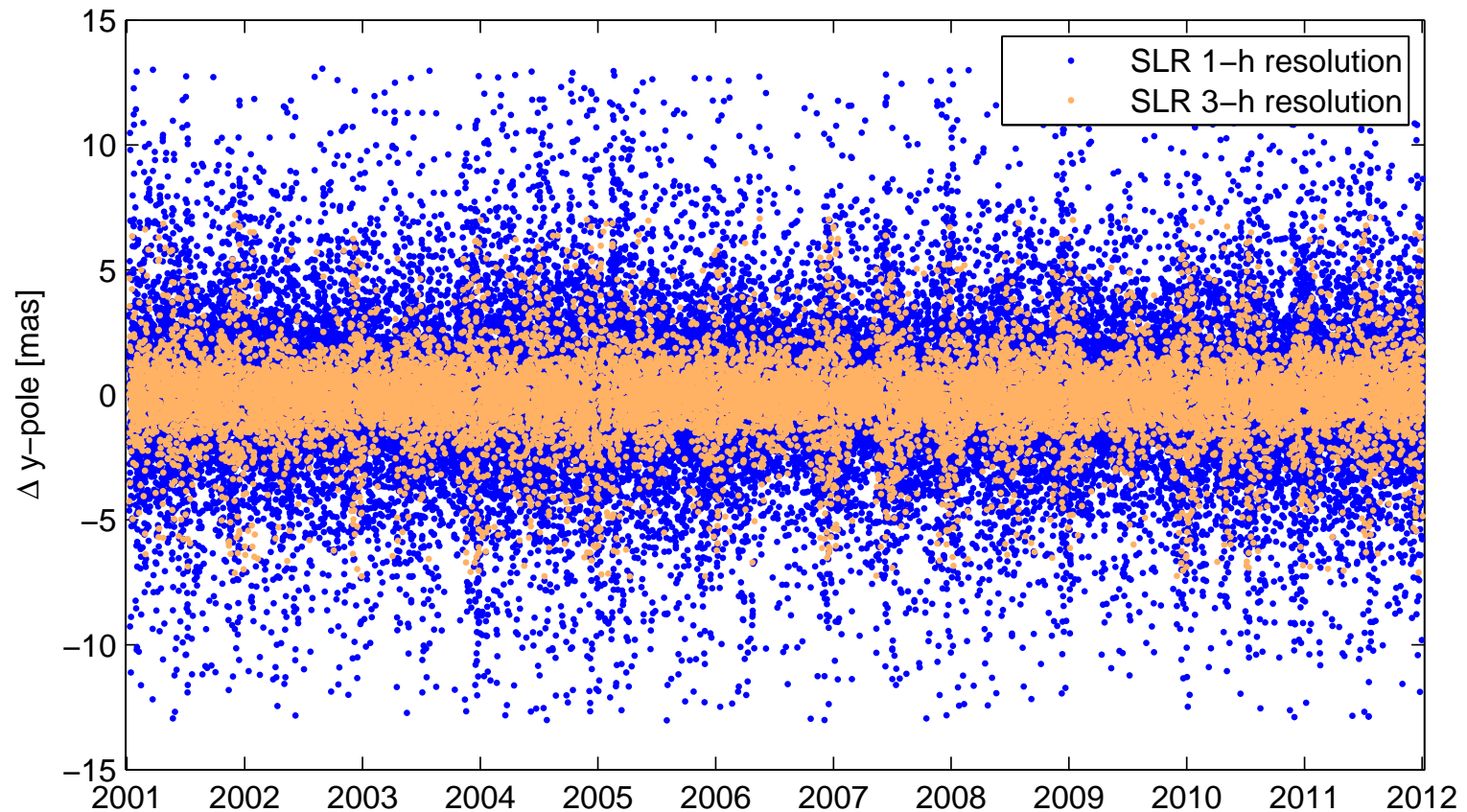


GLONASS: WRMS =  $372.6 \mu\text{s}$

GPS: WRMS =  $162.2 \mu\text{s}$

=> PM based on GLONASS  
is clearly noisier than PM  
based on GPS

# Sub-daily ERPs: Time series PM



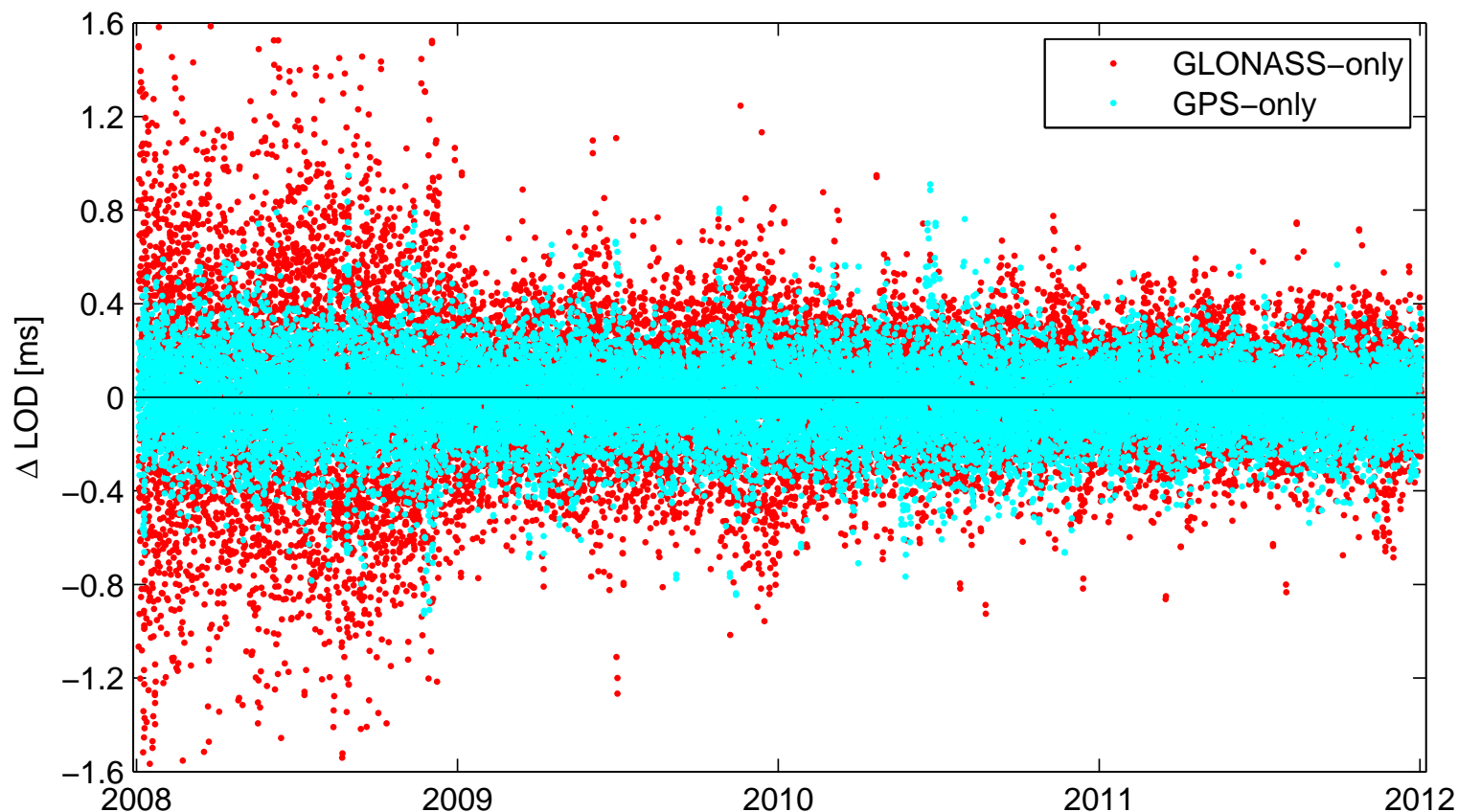
SLR 1-h: WRMS = 1648.6  $\mu$ as

SLR 2-h: WRMS = 1213.1  $\mu$ as (not shown)

SLR 3-h: WRMS = 1050.7  $\mu$ as

=> 1-hour  
resolution might be  
too high for SLR

# Sub-daily ERPs: Time series LOD

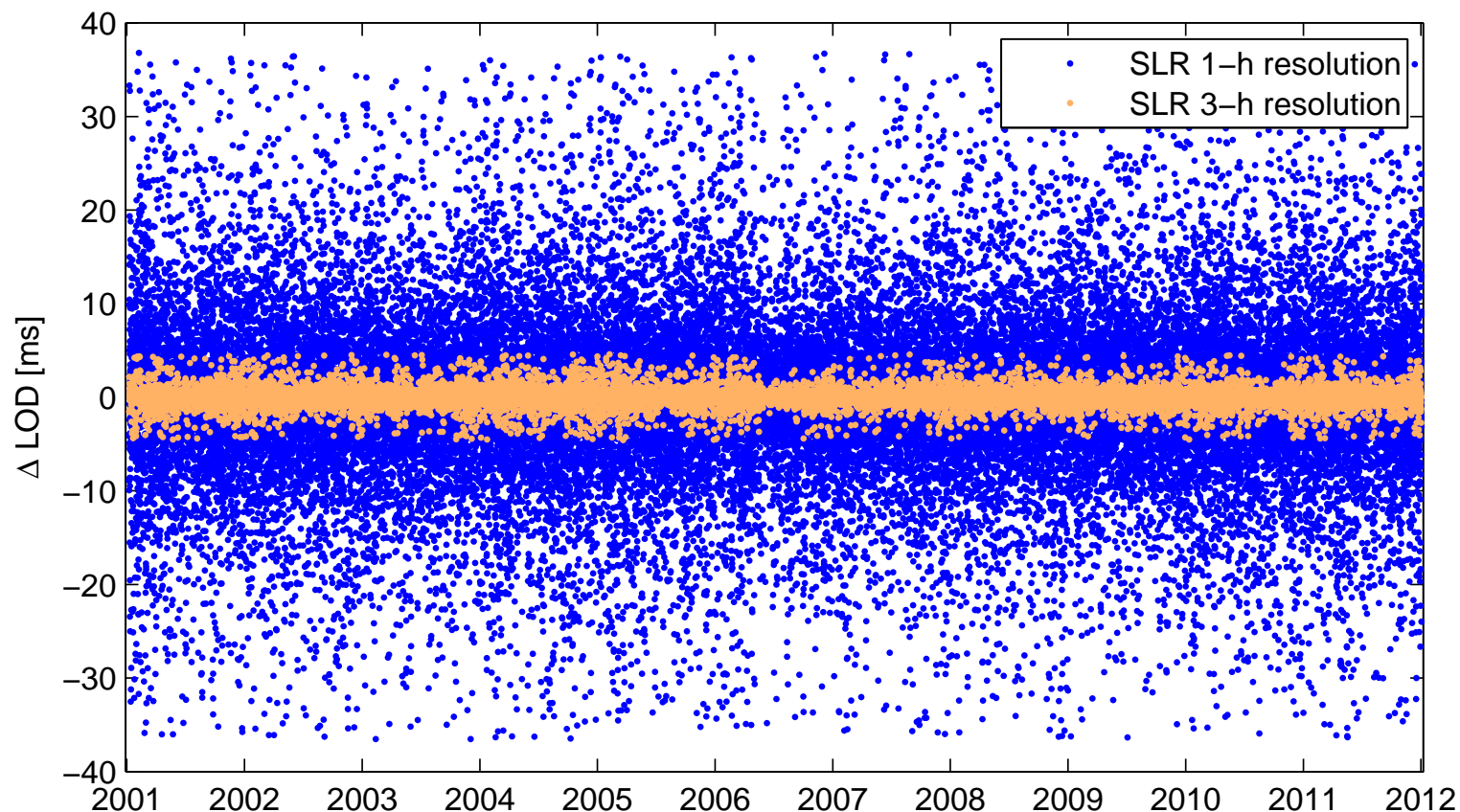


GLONASS: WRMS =  $229.5 \mu\text{s}$

GPS: WRMS =  $161.9 \mu\text{s}$

=> GLONASS has similar quality  
as GPS if full satellite  
constellation is available

# Sub-daily ERPs: Time series LOD



SLR 1-h: WRMS = 4380.0  $\mu\text{s}$

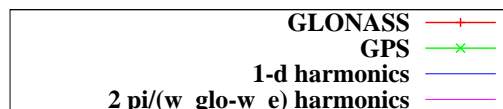
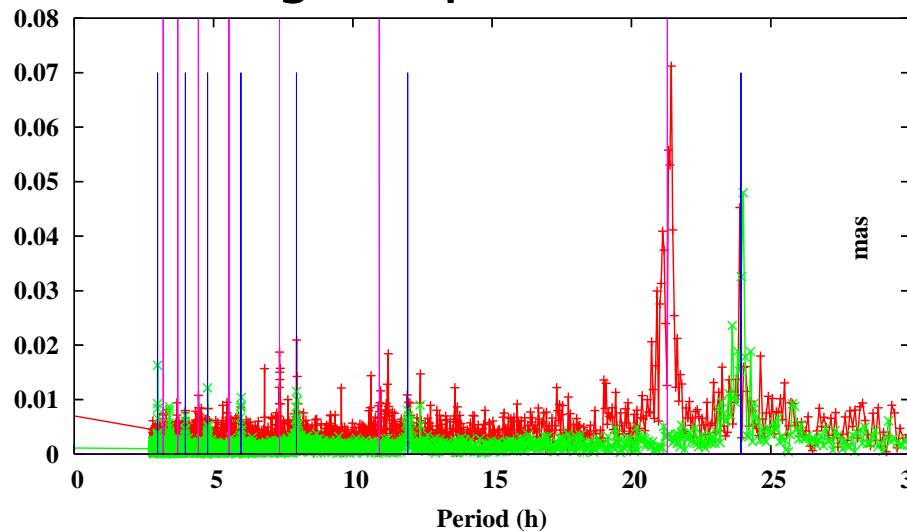
SLR 2-h: WRMS = 1171.3  $\mu\text{s}$

SLR 3-h: WRMS = 552.1  $\mu\text{s}$

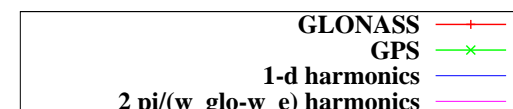
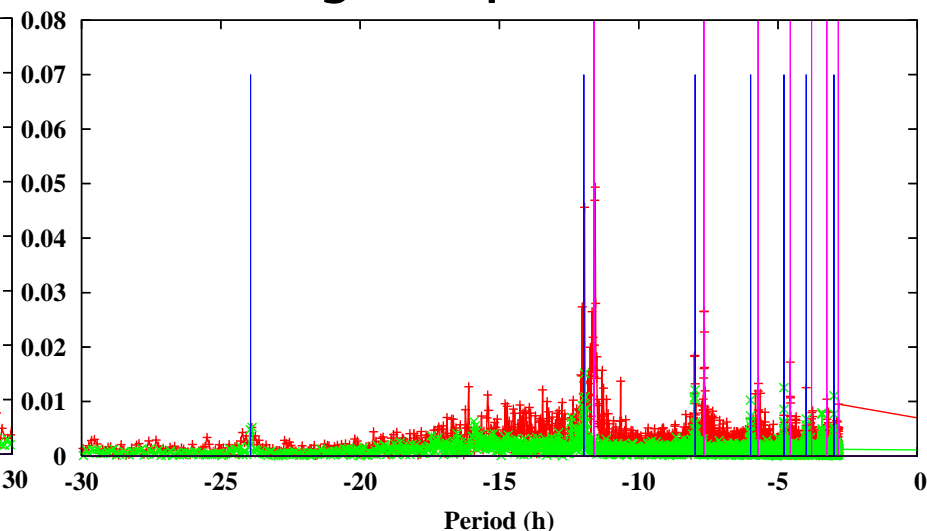
=> The temporal resolution has a bigger impact on LOD than on PM

# Sub-daily ERPs: Spectra of PM time-series

## Prograde polar motion



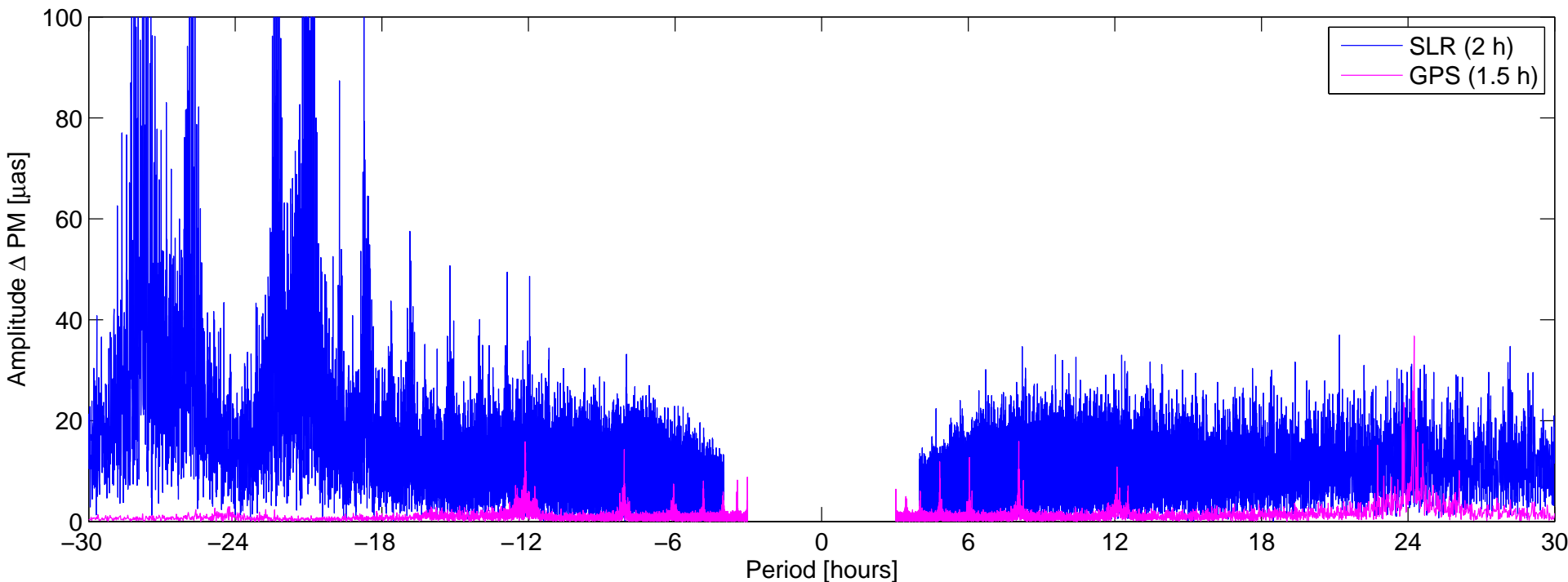
## Retrograde polar motion



- **GPS**: many orbital artefacts  
= harmonics of a **diurnal period**
- **GLONASS**: many orbital artefacts  
= harmonics of **linear combination** of the **Earth's** and the **satellites' revolution periods**



# Sub-daily ERPs: Spectra of PM time-series



## SLR-LAGEOS:

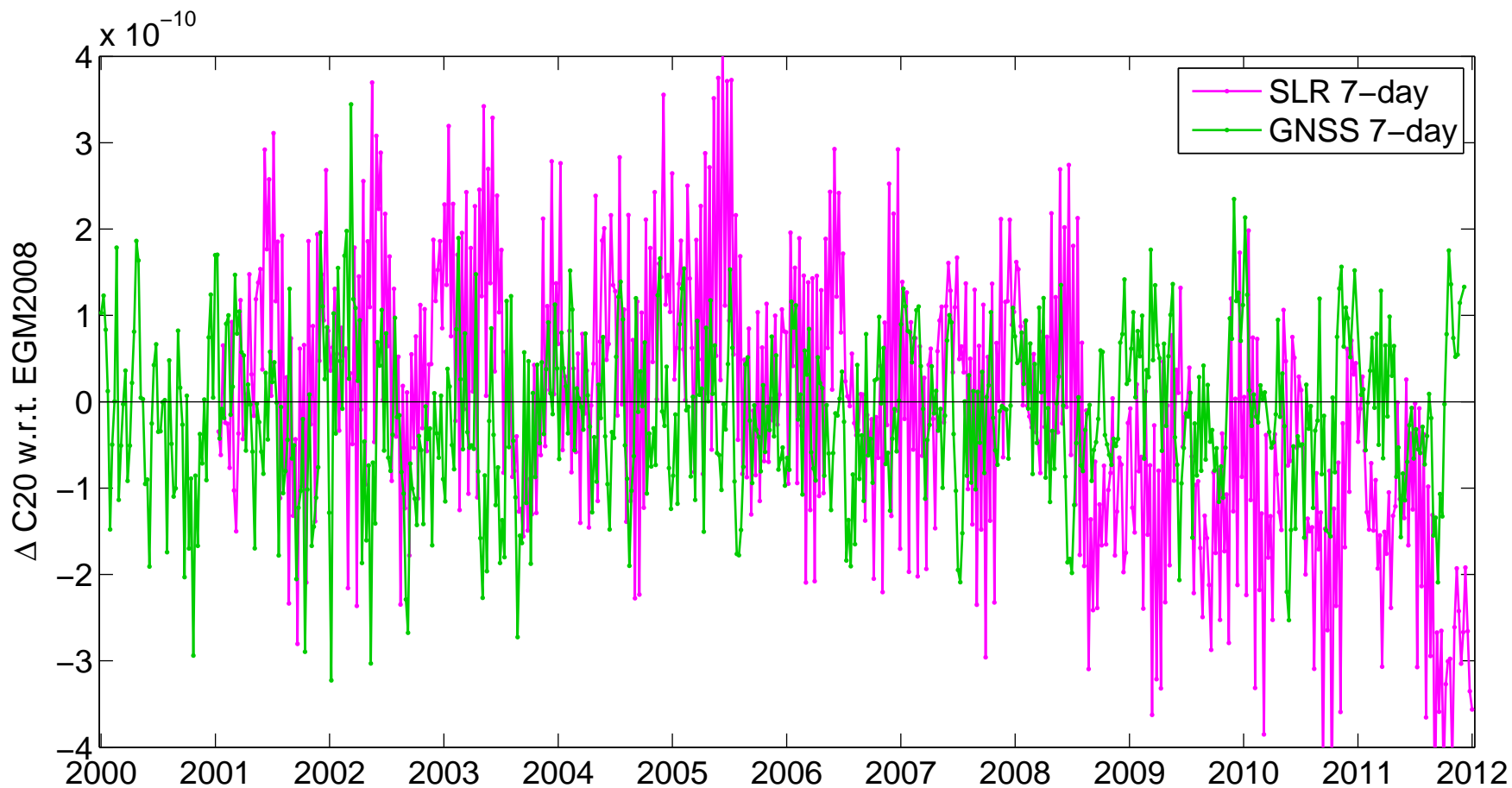
- Many artefacts in retrograde PM: **linear combinations** of **Earth's** and **satellites' revolution periods** (3.75 h)
- Prograde PM does not have artefacts (but much larger noise level than GNSS)

# Impact of low-degree gravity

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- **2 types of solution series** are computed:
  - **No** gravity field coefficients estimated  
(= «Standard» solution)
  - **C20** estimated
- **GNSS**: weekly solutions, 2000 – 2011
- **SLR**: weekly solutions, 2001 – 2011

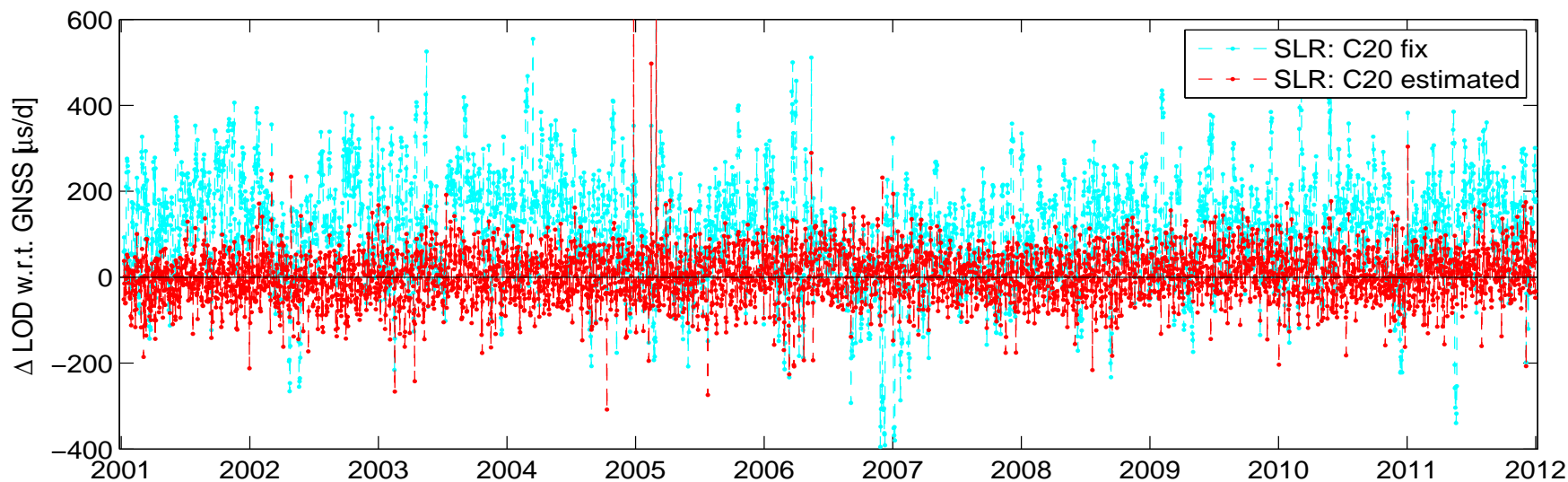
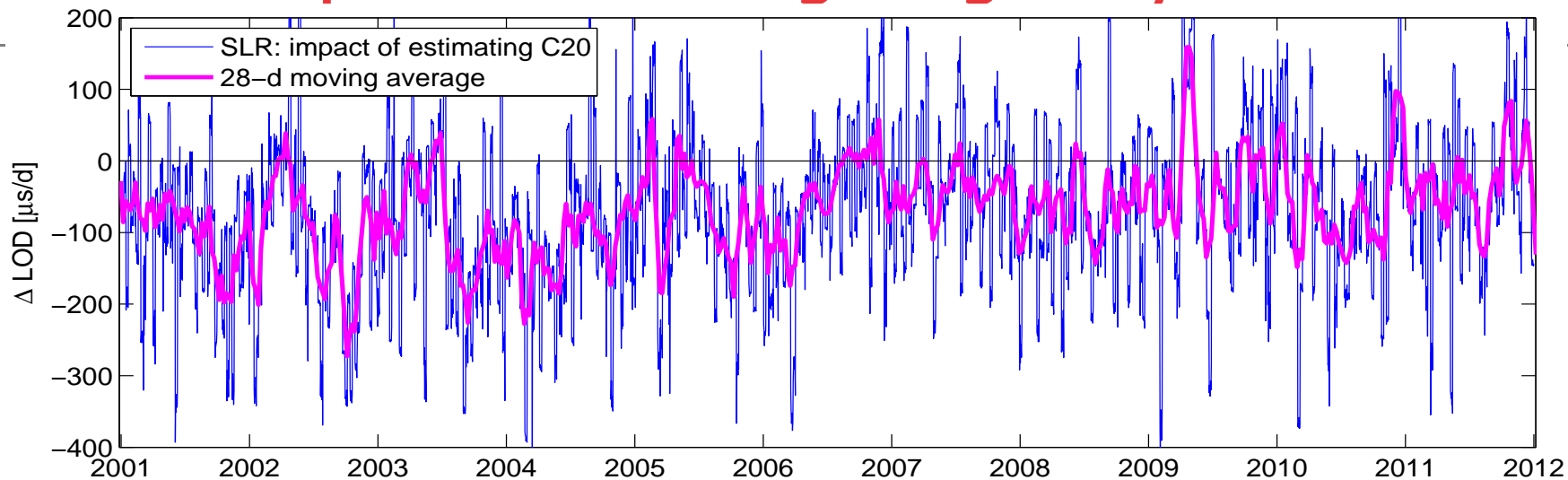
# Impact of low-degree gravity: C20



Variations are not negligible

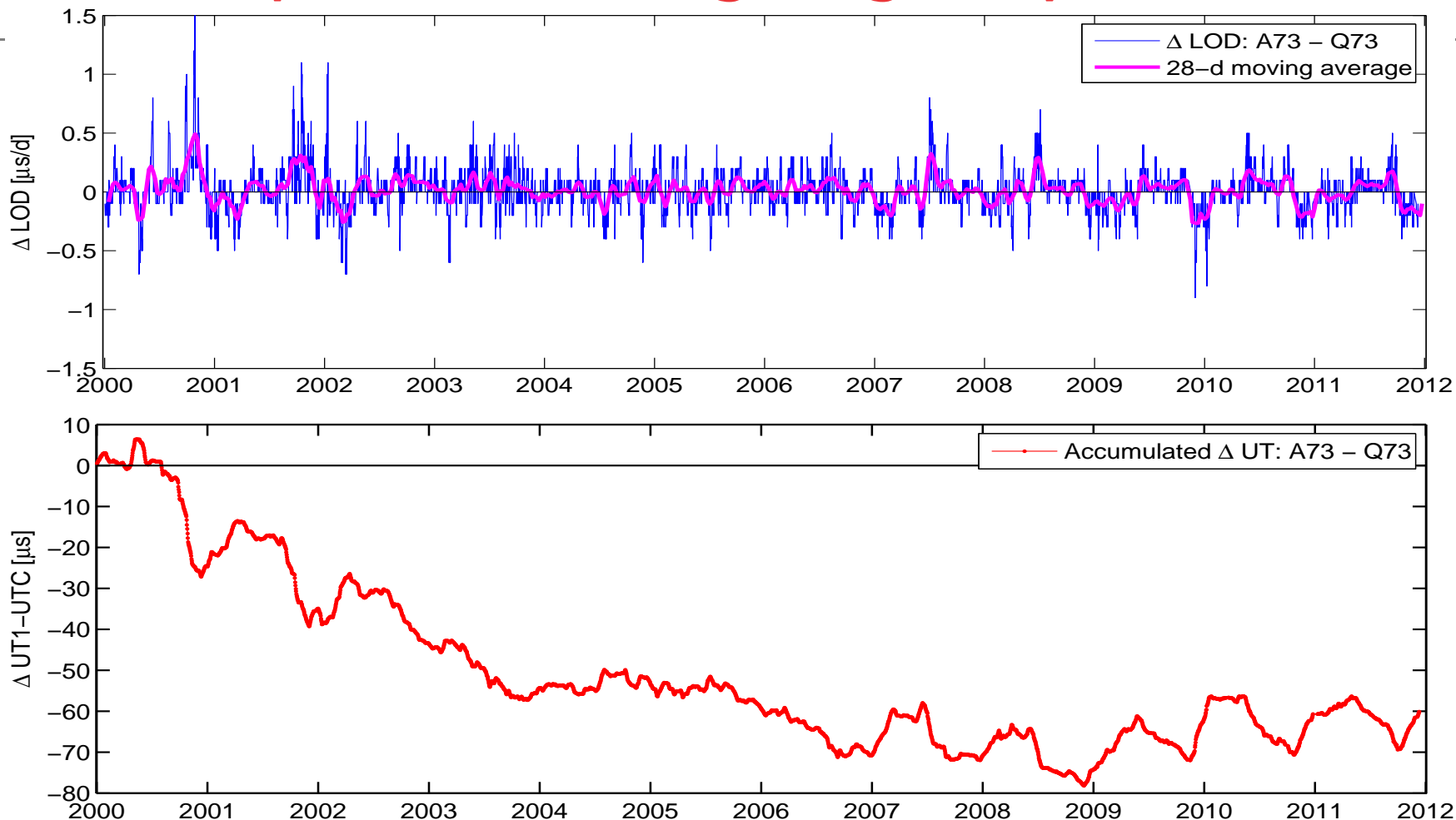
Formal errors:  $\sim 1.e-12$

# Impact of low-degree gravity: SLR



LOD is shifted if C20 is not estimated:  $\sim 74 \mu\text{s}$

# Impact of low-degree gravity: GNSS



Impact of estimating C20 on UT1–UTC / LOD seems to be small

**BUT: Accumulated effect is not negligible**

# Conclusions

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- **Sub-daily ERPs:**
  - Orbit-related artefacts in all satellite techniques
  - SLR capability is surprisingly good (considering the small amount of data)
  - 1-h resolution is too high for SLR, but 2-h resolution seems feasible
- **Impact of low-degree coefficients of the Earth's gravity field:**
  - Impact of C20 was studied
  - SLR: LOD is shifted by  $\sim 74 \mu\text{s}$
  - GNSS: Accumulated effect reaches  $\sim 70 \mu\text{s}$  after few years
  - Consequence: C20 should be estimated together with ERPs